# Subdata selection for big data regression: an improved approach

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February 25, 2022



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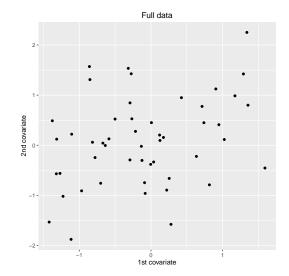
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## Discussion

References

- Big data analysis
- Computational power versus data volume
- Data reduction Keep the most informative data points
- Random selection (Drineas et al., 2011)
- Concept of optimal designs IBOSS approach (Wang et al., 2019)
- Orthogonal subsampling OSS approach (Wang et al., 2021)
- Orthogonal array (Ren and Zhao, 2021)

## Which data points should one select?



♦ Covariates (p): 2 ♦ Full data (n): 50 ♦ Subdata size (k): 8

Figure 1: Full data between two covariates.

# Motivation example

♦ Covariates (p): 2 ♦ Full data (n): 50 ♦ Subdata size (k): 8

Selection of data points with large convex hull

Selected data points can have a large volume

Maximize the determinant of the information matrix

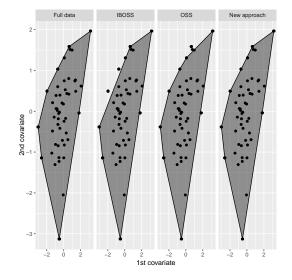


Figure 2: An example for the different approaches.

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## Theoretical considerations

- ♦ Linear regression model:  $y_i = \beta_0 + \mathbf{x}_i^\mathsf{T} \beta_1 + \epsilon_i$ , i = 1, 2, ..., n♦ Covariate vectors:  $\mathbf{x}_i = (x_{i1}, x_{i2}, ..., x_{ip})^\mathsf{T}$ , i = 1, 2, ..., n
- $\diamond$  Unknown parameters:  $\boldsymbol{\beta} = (\beta_0, \boldsymbol{\beta}_1^{\mathsf{T}})^{\mathsf{T}}, \boldsymbol{\beta}_1 = (\beta_1, \beta_2, \dots, \beta_p)^{\mathsf{T}}$ 
  - Under full data

$$\hat{\boldsymbol{\beta}}_{\mathsf{Full}} = \left(\sum_{i=1}^{n} \mathbf{z}_{i} \mathbf{z}_{i}^{\mathsf{T}}\right)^{-1} \sum_{i=1}^{n} \mathbf{z}_{i} y_{i}, \quad \mathbf{z}_{i} = (1, \mathbf{x}_{i}^{\mathsf{T}})^{\mathsf{T}}$$
$$\mathbf{Q}_{\mathsf{Full}} = \frac{1}{\sigma^{2}} \sum_{i=1}^{n} \mathbf{z}_{i} \mathbf{z}_{i}^{\mathsf{T}}$$

Under subdata

$$\hat{\boldsymbol{\beta}}_{\mathsf{Sub}} = \left(\sum_{i=1}^{n} \delta_i \mathbf{z}_i \mathbf{z}_i^{\mathsf{T}}\right)^{-1} \sum_{i=1}^{n} \delta_i \mathbf{z}_i y_i$$
$$\mathbf{Q}_{\mathsf{Sub}} = \frac{1}{\sigma^2} \sum_{i=1}^{n} \delta_i \mathbf{z}_i \mathbf{z}_i^{\mathsf{T}}$$
$$\delta_i = \begin{cases} 1, & \text{if } (\mathbf{x}_i, y_i) \text{ is included} \\ 0, & \text{if } (\mathbf{x}_i, y_i) \text{ is not included} \end{cases}, \sum_{i=1}^{n} \delta_i = k$$

## Generalized variance

 $\diamond \mathbf{x}_i^*$ : *j*th covariate under the selected subdata

$$\det \left(\mathbf{Q}_{Sub}\right) = \frac{k^{p+1}}{\sigma^{2(p+1)}} \det \left( \begin{bmatrix} s_{\mathbf{x}_{1}^{*}}^{*} & s_{\mathbf{x}_{1}^{*}\mathbf{x}_{2}^{*}}^{*} & \cdots & s_{\mathbf{x}_{1}^{*}\mathbf{x}_{p}^{*}}^{*} \\ s_{\mathbf{x}_{1}^{*}\mathbf{x}_{2}^{*}}^{*} & s_{\mathbf{x}_{2}^{*}}^{*} & \cdots & s_{\mathbf{x}_{2}^{*}\mathbf{x}_{p}^{*}}^{*} \\ \vdots & \vdots & \ddots & \vdots \\ s_{\mathbf{x}_{1}^{*}\mathbf{x}_{p}^{*}}^{*} & s_{\mathbf{x}_{2}^{*}\mathbf{x}_{p}^{*}}^{*} & \cdots & s_{\mathbf{x}_{p}^{*}}^{*} \end{bmatrix} \right)$$
$$\bar{\mathbf{x}}_{j}^{*} = \frac{\sum_{i=1}^{n} \delta_{i} x_{ij}}{k}, \ s_{\mathbf{x}_{j}^{*}}^{*} = \frac{\sum_{i=1}^{n} \delta_{i} (x_{ij} - \bar{\mathbf{x}}_{j}^{*})^{2}}{k}, \ s_{\mathbf{x}_{j}^{*}\mathbf{x}_{t}^{*}}^{*} = \frac{\sum_{i=1}^{n} \delta_{i} x_{ij} x_{it}}{k} - \bar{\mathbf{x}}_{j}^{*} \bar{\mathbf{x}}_{t}^{*}$$
Cholesky decomposition

**Theorem 1.** The generalized variance of covariates under the subdata is maximized by the selection of data points for which  $s_{\mathbf{x}_{j}^{*}}^{2}$  is maximized for any j = 1, 2, ..., p, and  $s_{\mathbf{x}_{o}^{*}\mathbf{x}_{j}^{*}} = 0$  for any j > o = 1, 2, ..., j-1, simultaneously.

The information-based optimal subdata selection (IBOSS) approach
D-optimality

♦ Selection of data points with the smallest and largest values of all covariates sequentially

- The orthogonal subsampling (OSS) approach
  - $\diamond$  A two-level OA represents an optimal design for linear regression

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- ♦ D- and A-optimality
- $\diamond$  All covariates are scaled to [-1,1]
- ♦ Elimination algorithm based on a discrepancy function

Extreme values: data points at the corners of the data domain

Combinatorial orthogonality: data points are as dissimilar as possible

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Algorithm 1 Alg1 **Input:** subdata  $\mathbf{S} = (\mathbf{s}_i), i = 1, 2, \dots, k$  of the OSS approach, initial full data  $\mathbf{D}_{\text{Full}}$ , subdata size k, candidate data points K from each covariate **Output:** new obtained subdata **S** Step 1: Preperation  $\mathbf{S} = \text{convert}(\mathbf{S})$  $\triangleright$  convert subdata **S** to their initial values  $V = \det(\mathbf{Q}_{Sub})$  $\triangleright$  generalized variance of **S**  $\mathbf{D} = \mathbf{D}_{\text{Full}} - \mathbf{S} = (d_{ri})$   $\triangleright$  remaining data points  $\mathbf{d}_{r} = (d_{r1}, \dots, d_{rp}) \notin \mathbf{S}$  $\triangleright$  number of data points  $\mathbf{d}_{r} \in \mathbf{D}$  $N_{\rm F} = {\rm nrow}({\bf D})$  $\mathbf{F} = \mathbf{\emptyset}$ ▷ initialize the index set of candidate data points Step 2: Find candidate data points for *j* in 1, . . . , *p* do  $\mathbf{d}_{i} = \operatorname{sort}(\mathbf{d}_{i})$  $\triangleright$  sort  $\mathbf{d}_{i} = (d_{1i}, \ldots, d_{N_{\mathsf{E}}i})$  $\mathbf{D} = \operatorname{sort}(\mathbf{D})$  $\triangleright$  sort **D** based on **d**.  $\mathbf{F} = \mathbf{F} \cup \mathbf{d}_{1} \cup \cdots \cup \mathbf{d}_{K/2}$  $\mathbf{F} = \mathbf{F} \cup \mathbf{d}_{N_{\mathsf{F}} - \mathcal{K}/2 + 1} \cup \cdots \cup \mathbf{d}_{N_{\mathsf{F}}}.$ end for  $\mathbf{F} = unique(\mathbf{F})$  $\triangleright$  keep unique data points of  $\mathbf{F} = (\mathbf{f}_w)$  $N_{\rm F} = {\rm nrow}({\bf F})$  $\triangleright$  number of data points  $\mathbf{f}_w \in \mathbf{F}$ Step 3: Main algorithm for *i* in 1, ..., *k* do for w in  $1, \ldots, N_{\mathsf{F}}$  do  $\mathbf{s}_i \leftrightarrow \mathbf{f}_w$  $\triangleright$  interchange data points  $\mathbf{s}_i$  and  $\mathbf{f}_w$  $V_{\text{new}} = \det(\mathbf{Q}_{\text{Sub}})$ ▷ generalized variance of new S if  $V_{\text{new}} > V$  then  $V = V_{\text{new}}$ break else  $\mathbf{s}_i \leftrightarrow \mathbf{f}_{\mathbf{w}}$ end if end for end for

return S

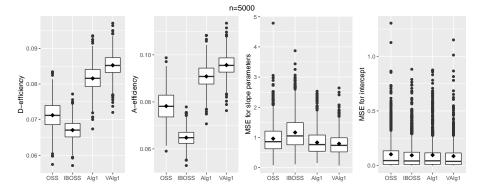
# VAlg1

 $\diamond$  Change as to which  $\mathbf{f}_w$  is interchanged with  $\mathbf{s}_i$ 

#### Algorithm 2 VAlg1 Steps 1 and 2: Same as in Alg1 Step 3: Main algorithm for *i* in 1, . . . , *k* do for w in $1, \ldots, N_{\mathsf{F}}$ do $\mathbf{s}_i \leftrightarrow \mathbf{f}_w$ $\triangleright$ interchange data points $\mathbf{s}_i$ and $\mathbf{f}_w$ $V_{\text{new}} = \det(\mathbf{Q}_{\text{Sub}})$ ▷ generalized variance of new S if $V_{\text{new}} > V$ then $V = V_{\text{new}}$ else $\mathbf{s}_i \leftrightarrow \mathbf{f}_w$ end if end for end for return S

## Evaluation of algorithms (1)

♦ Alg1: 5 iterations - VAlg1: 1 iteration



# Evaluation of algorithms (2)

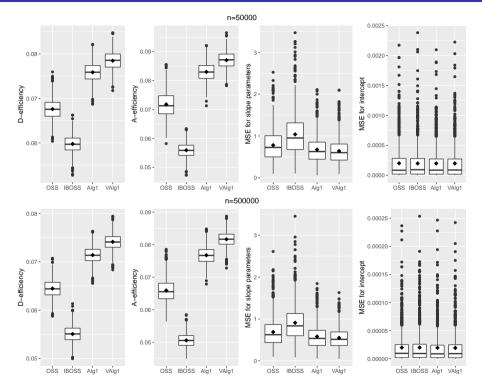


Figure 3: The MSEs, D- and A-efficiencies for the subdata selected by different approaches.

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## Execution time of Alg1

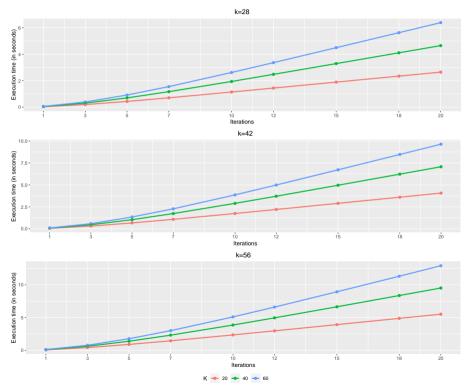


Figure 4: The mean execution time (in seconds) of Alg1.

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## Execution time of VAlg1

- ♦ 500 simulations
- $\diamond 1$  iteration

k	28	28	28	42	42	42	56	56	56
K	20	40	60	20	40	60	20	40	60
Time	0.2244	0.39534	0.5611	0.3361	0.5989	0.8321	0.4593	0.8226	1.1368

Table 1: The mean execution time (in seconds) of VAlg1.

## About iterations of Alg1

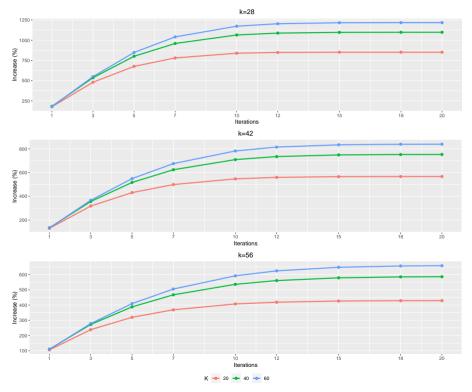


Figure 5: The mean percent increase in the generalized variance by Alg1.

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# Power consumption data (Salam and Hibaoui, 2018)

♦  $y_i$ : power consumption of the 2<sup>*nd*</sup> zone of Tetouan city (north Morocco) ♦ n = 52,417 data points

 $\diamond$  p=5: temperature, humidity, wind speed, diffuse flows and general diffuse flows

♦ 1000 bootstrap samples

 $\diamond$  K = 10, Alg1: 5 iterations - VAlg1: 1 iteration

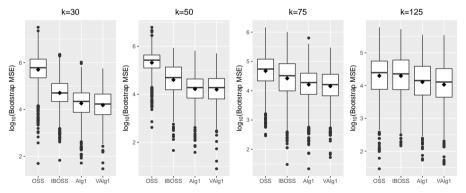


Figure 6: The bootstrap MSEs for estimating slope parameters by different approaches.

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# Chemical sensors data (Fonollosa et al., 2015)

 $\diamond y_i$ : readings of a chemical sensor exposed to the mixture of Ethylene and CO at varying concentrations in air

 $\diamond$  *n* = 4, 188, 261 data points

 $\diamond p = 14$ : readings of 14 chemical sensors exposed to the mixture of

Ethylene and CO at varying concentrations in air

◊ k = 140, K = 10

♦ Alg1: 5 iterations - VAlg1: 1 iteration

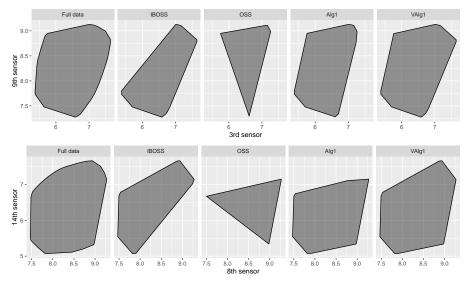


Figure 7: The convex hulls between the 9th and the 3rd sensor, as well as between the 14th and the 8th sensor, for the subdata selected by different approaches.

♦ Which approach should one prefer?

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# Thank you for your attention!